

Analyzing Adaptive Parameter Landscapes in Parameter Adaptation Methods for Differential Evolution

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Differential Evolution (DE) [Storn 97]: A simple black-box optimizer

DE is sensitive to the setting of two parameters: F and C

- Scale factor F controls the magnitude of the differential mutation
- Crossover rate C controls the number of inherited variables from x

Adaptive DE algorithms

- E.g., jDE [Brest 06], JADE [Zhang 09], SHADE [Tanabe 13]
- adaptively adjust F and C values

Poor understanding of parameter adaptation mechanisms in DE

- Its working principle is unclear
- Only a few previous studies tried to analyze adaptive DEs
 - E.g., [Zielinski 08, Drozdik 15, Tanabe 16, Tanabe 17, Tanabe 20]

Difficulty comes from the unclarity of the adaptive parameter space

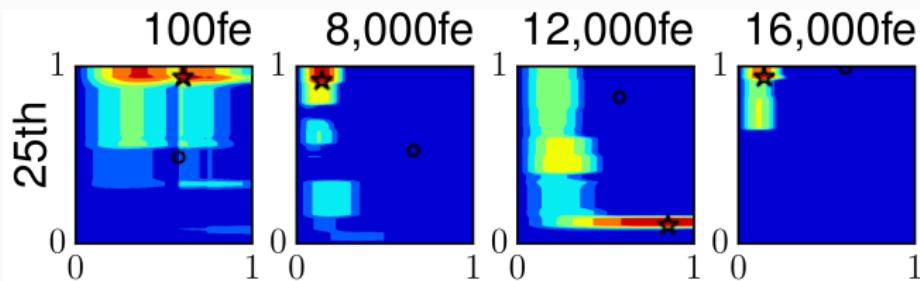
- Is it possible to make the adaptive parameter space “visualizable”?

Contributions

This work

1. proposes a concept called **adaptive parameter landscapes**
2. proposes a method of analyzing adaptive parameter landscapes
3. provides insightful knowledge on parameter adaptation in DE

Visualization of dynamically changing parameter landscapes



Fitness landscape analysis

Fitness landscape [Pitzer 12]

$$\mathcal{L}_{\text{fitness}} = (\mathbb{X}, f, D)$$

- \mathbb{X} : solution space, f : objective function, D : distance function

No explanation needed in GECCO

Parameter landscape analysis

Parameter landscape [Harrison 19]

$$\mathcal{L}_{\text{parameter}} = (\Theta, M, D),$$

- Θ : parameter space, M : performance metric, D : distance function
- $\mathcal{L}_{\text{parameter}}$ is an $\mathcal{L}_{\text{fitness}}$ of a parameter tuning problem

Example: parameter tuning of $F \in [0, 1]$ and $C \in [0, 1]$ in DE

- to find the best pair $(F, C) \in \Theta$ on a training problem set I
- $\Theta = [0, 1] \times [0, 1]$, M : ERT on I , D : Euclidean distance

Parameter landscapes coined in [Yuan 12] are also known as

- performance landscapes [Yuan 07], meta-fitness landscapes [Pedersen 10], utility landscapes [Eiben 11], ERT landscapes [Belkhir 16], parameter configuration landscapes [Harrison 19], and algorithm configuration landscapes [Pushak 18]
- No consistency in the terminology in the EC community

Proposed concept: adaptive parameter landscapes

Parameter landscape [Harrison 19]

$$\mathcal{L}_{\text{parameter}} = (\Theta, M, D)$$

Adaptive parameter landscape

$$\mathcal{L}_{\text{adaptive}} = (\Theta_i^t, M, D)$$

- Θ_i^t : dynamic parameter space of x_i^t , M : performance metric, D : distance function
- $\mathcal{L}_{\text{adaptive}}$ is an $\mathcal{L}_{\text{parameter}}$ of the i -th individual at iteration t (x_i^t)
- While $\mathcal{L}_{\text{parameter}}$ is static, $\mathcal{L}_{\text{adaptive}}$ is dynamic

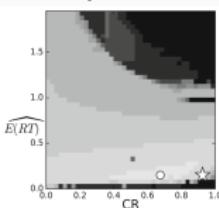
Example: parameter adaptation of $F \in [0, 1]$ and $C \in [0, 1]$ in DE

- to find the best pair $(F_i^t, C_i^t) \in \Theta_i^t$ for x_i^t
- $\Theta_i^t = [0, 1] \times [0, 1]$, M : G1 (explained later), D : Euclidean distance

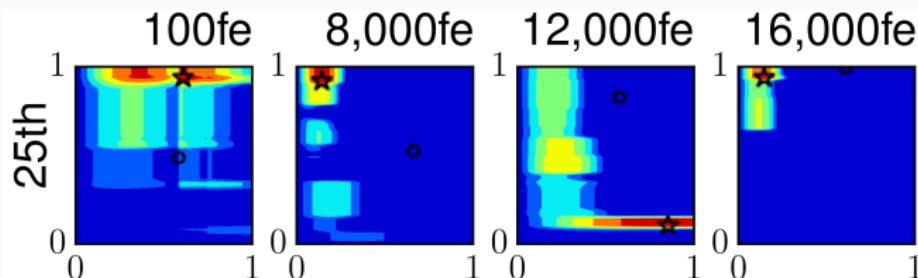
Parameter landscapes vs. adaptive parameter landscapes (F and C in DE)

Parameter landscape $\mathcal{L}_{\text{parameter}} = (\Theta, M, D)$ is **STATIC**

Parameter landscape of DE [Belkhir 16]



Adaptive parameter landscape $\mathcal{L}_{\text{adaptive}} = (\Theta_i^t, M, D)$ is **DYNAMIC**



Parameter landscapes vs. adaptive parameter landscapes (continued)

What the parameter landscape analysis focuses on

What the *adaptive* parameter landscape analysis focuses on

Overall search process

1st iteration

1st individual

2nd individual

2nd iteration

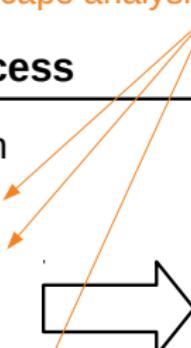
1st individual

2nd individual

μ -th individual

μ -th individual

⋮



NOT proposed: 1-step-lookahead greedy improvement metric (G1)

Nomenclature

- \mathbf{x}_i^t : the i -th individual in the population at iteration t
- \mathbf{u}_i^t : the i -th child generated by \mathbf{x}_i^t at iteration t
- F_i^t : the scale factor value used for generating \mathbf{u}_i^t
- C_i^t : the crossover rate value used for generating \mathbf{u}_i^t

G1 measures how much F_i^t and C_i^t improve the fitness value of \mathbf{x}_i^t

$$\text{G1}(\mathbf{F}_i^t, \mathbf{C}_i^t) = \begin{cases} |f(\mathbf{x}_i^t) - f(\mathbf{u}_i^t)| & \text{if } f(\mathbf{u}_i^t) < f(\mathbf{x}_i^t) \\ 0 & \text{otherwise} \end{cases}$$

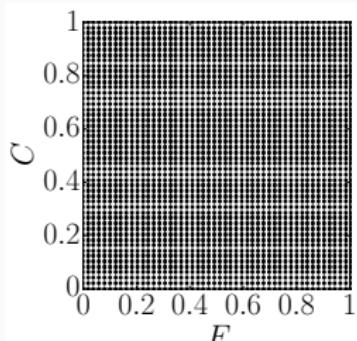
- If $f(\mathbf{x}_i^t) = 10$ and $f(\mathbf{u}_i^t) = 3$, $\text{G1}(F_i^t, C_i^t) = 7$
- If $f(\mathbf{x}_i^t) = 10$ and $f(\mathbf{u}_i^t) = 30$, $\text{G1}(F_i^t, C_i^t) = 0$
- Just for the sake of simplicity, we use the term “G1”
- G1 can be replaced with G2, G3, and G1 + novelty

Proposed method for analyzing adaptive parameter landscapes

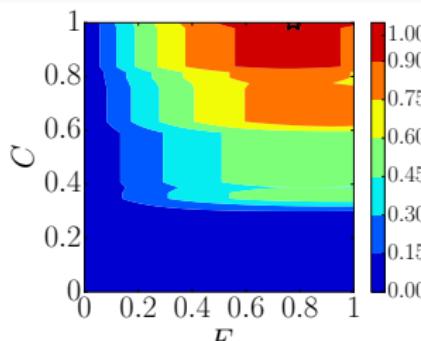
For the i -th individual at iteration t (x_i^t)

1. Generate $50 \times 50 = 2500$ pairs of F and C in a grid manner
2. Generate 2500 children by using the 2500 pairs of F and C
 - Same random numbers are used for generating the 2500 children
3. Evaluate the objective function values of the 2500 children
 - Extra 2500 function evaluations are *not counted*
4. Calculate the G1 values of the 2500 pairs

(a) 50×50 pairs



(b) Contour map of $\mathcal{L}_{\text{adaptive}}$



Properties of the proposed method

Proposed method is totally independent from the procedure of DE

- Proposed method is just a logger, not an optimizer
- 2500 children are used only for the analysis, not for the search
- Behavior of DE with/without the proposed method is the same

Suppression strategy of the randomness in DE

- 1 child for the actual search and 2500 children for the G1 calculation are generated using the same parents and crossover mask
- Stochastic nature of DE can be suppressed

Cheat in not counting the 2500 extra function evaluations

- This cheat is no problem at all for the analysis
- We are not interested in solving any real-world problem

Experimental setup

Settings for adaptive DEs

- jDE [Brest 06], JADE [Zhang 09], SHADE [Tanabe 13]
- Default hyperparameter settings
- Population size $\mu = 100$, no restart
- Current-to- p best/1 [Zhang 09], binomial crossover [Storn 97]

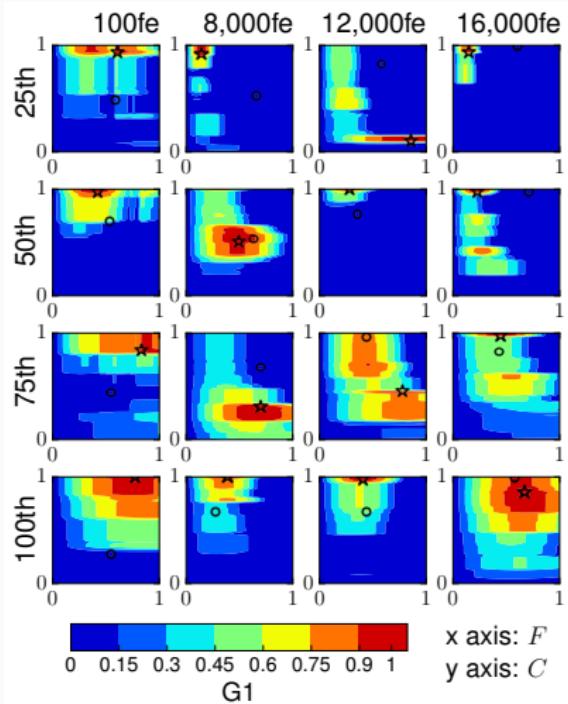
Settings for test functions

- 24 BBOB noiseless functions [Hansen 09] in COCO [Hansen 16]
- Dimensionality $n \in \{2, 3, 5, 10, 20, 40\}$
- Maximum number of evaluations = $10\,000 \times n$
- Number of runs = 15 (results of a single run are shown)

Source code is available:

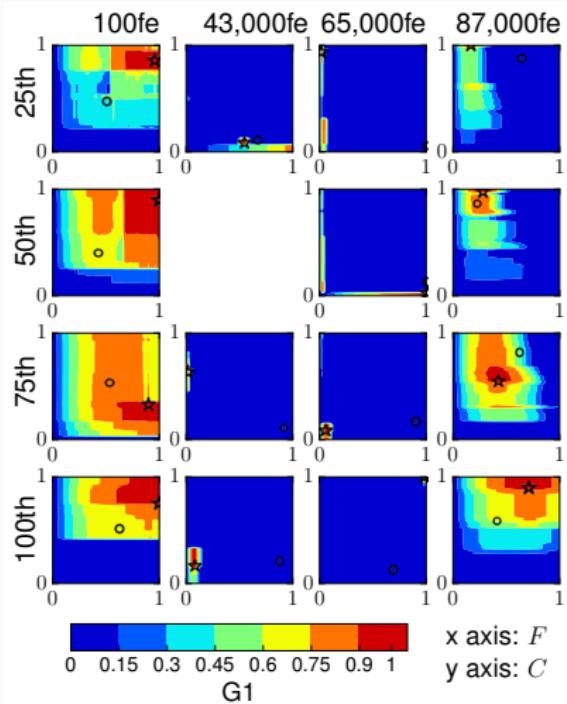
- <https://github.com/ryojitanabe/APL>

Contour maps of adaptive parameter landscapes in SHADE on the 20-dimensional Sphere function (f_1)



- 100 individuals were sorted
- Pairs for the best (1st) individual are seldom successful, so omitted it
- SHADE found x^* at $\approx 16\,000$ fe
- ○: the pair generated by SHADE
- ★: the best pair regarding G1
- Shape of $\mathcal{L}_{\text{adaptive}}$ is different depending on:
 - the rank of each individual
 - the search progress
- ○ and ★ are far from each other
- $\mathcal{L}_{\text{adaptive}}$ is unimodal/multimodal?

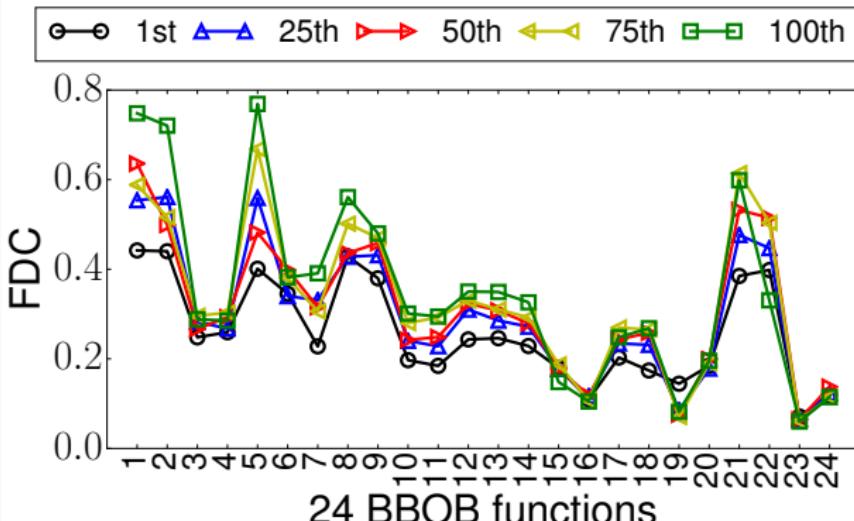
Contour maps of adaptive parameter landscapes in SHADE on the 20-dimensional Rastrigin function (f_3)



- Generating a successful pair on f_3 is more difficult than that on f_1
- $\mathcal{L}_{\text{adaptive}}$ at 100 fe looks easy
 - Area with $G1 > 0$ is large
- $\mathcal{L}_{\text{adaptive}}$ at 43 000 fe looks hard
 - Area with $G1 > 0$ is very small like needle-in-haystack land.
 - When all 2 500 pairs obtain $G1 = 0$, $\mathcal{L}_{\text{adaptive}}$ is not shown
- $\mathcal{L}_{\text{adaptive}}$ at 87 000 fe looks easy
 - Area with $G1 > 0$ values becomes large again
 - SHADE found x^* at $\approx 87\,000$ fe
 - Population has converged to x^*
 - Generating better children is easy

Average FDC values of adaptive parameter landscapes in SHADE ($n = 20$)

- Results of FDC [Jones 95] and Dispersion [Lunacek 06] are similar
- FDC value is different depending on the function
- $\mathcal{L}_{\text{adaptive}}$ of individuals with similar ranks have similar FDC values
 - E.g., FDC values of the 75th and 100th individuals are similar
- Global structures of $\mathcal{L}_{\text{adaptive}}$ can correlate with the rank of indiv.



Conclusion

This work

- proposed the concept called adaptive parameter landscapes $\mathcal{L}_{\text{adaptive}}$
- proposed the method of analyzing adaptive parameter landscapes
- provided insightful knowledge on parameter adaptation in DE

Our observations

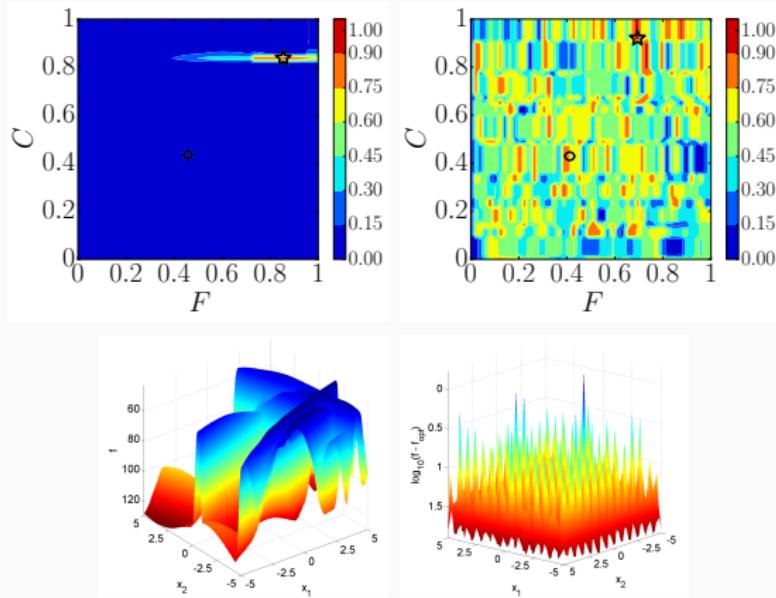
- $\mathcal{L}_{\text{adaptive}}$ is different depending on the search progress
- $\mathcal{L}_{\text{adaptive}}$ is influenced by the properties of a problem
- Global structures of $\mathcal{L}_{\text{adaptive}}$ can correlate with the rank of indiv.
- ADEs generally generate a pair of F and C far from the best pair

Future work

- analyze other adaptive evolutionary algorithms, e.g., GA and ES
- use other performance metric, e.g., G2 and G1+novelty

Contour maps of adaptive parameter landscapes in SHADE on the 20-dimensional Gallagher and Katsuura functions (f_{22} and f_{23})

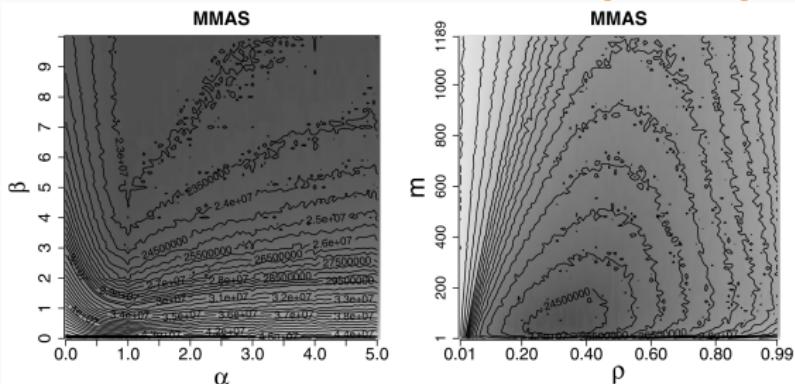
- Results of the 100-th individual at 100 evaluations
- Shape of adaptive parameter landscapes is significantly influenced by the global structures of fitness landscapes



[Hansen 09]

Parameter landscape analysis

Parameter landscapes of MMAS [Yuan 12]



Motivation

- A better understanding of $\mathcal{L}_{\text{parameter}}$ can lead to a better understanding of the corresponding optimizer
 - making the optimizer more efficient
- Knowledge on $\mathcal{L}_{\text{parameter}}$ are useful for designing a parameter tuner

Basic DE with almost any parameter adaptation method

input: $\mathbb{X} \subseteq \mathbb{R}^n$, $f : \mathbb{R}^n \rightarrow \mathbb{R}$, population size μ , some hyperparameters

$t \leftarrow 1$, initialize $P = \{x_1, \dots, x_\mu\}$ randomly;

Initialize internal parameters for adaptation of F and C ;

while The termination criteria are not met **do**

for $i \in \{1, \dots, \mu\}$ **do**

 Generate F_i and C_i ;

 Randomly select r_1, r_2, r_3 from $\{1, \dots, \mu\} \setminus \{i\}$ s.t. $r_1 \neq r_2 \neq r_3$;

 Mutant vector $v_i \leftarrow x_{r_1} + F_i (x_{r_2} - x_{r_3})$;

 Child $u_i = (u_{i,1}, \dots, u_{i,n})^\top$, randomly select j_{rand} form $\{1, \dots, n\}$;

for $j \in \{1, \dots, n\}$ **do**

if $\text{rand}[0, 1] \leq C_i$ **or** $j = j_{\text{rand}}$ **then** $u_{i,j} \leftarrow v_{i,j}$;

else $u_{i,j} \leftarrow x_{i,j}$;

for $i \in \{1, \dots, \mu\}$ **do**

if $f(u_i) \leq f(x_i)$ **then** $x_i \leftarrow u_i$;

Update internal parameters for adaptation of F and C ;

$t \leftarrow t + 1$;

Basic DE [Storn 97]

input: $\mathbb{X} \subseteq \mathbb{R}^n$, $f : \mathbb{R}^n \rightarrow \mathbb{R}$, population size μ , scale factor F , crossover rate C
 $t \leftarrow 1$, initialize $\mathbf{P} = \{\mathbf{x}_1, \dots, \mathbf{x}_\mu\}$ randomly;

while The termination criteria are not met **do**

for $i \in \{1, \dots, \mu\}$ **do**

 Randomly select r_1, r_2, r_3 from $\{1, \dots, \mu\} \setminus \{i\}$ s.t. $r_1 \neq r_2 \neq r_3$;

 Mutant vector $\mathbf{v}_i \leftarrow \mathbf{x}_{r_1} + F(\mathbf{x}_{r_2} - \mathbf{x}_{r_3})$;

 Child $\mathbf{u}_i = (u_{i,1}, \dots, u_{i,n})^\top$, randomly select j_{rand} form $\{1, \dots, n\}$;

for $j \in \{1, \dots, n\}$ **do**

if $\text{rand}[0, 1] \leq C$ **or** $j = j_{\text{rand}}$ **then** $u_{i,j} \leftarrow v_{i,j}$;

else $u_{i,j} \leftarrow x_{i,j}$;

for $i \in \{1, \dots, \mu\}$ **do**

if $f(\mathbf{u}_i) \leq f(\mathbf{x}_i)$ **then** $\mathbf{x}_i \leftarrow \mathbf{u}_i$;

$t \leftarrow t + 1$;

Basic DE with the parameter adaptation method in JADE [Zhang 09]

input: $\mathbb{X} \subseteq \mathbb{R}^n$, $f : \mathbb{R}^n \rightarrow \mathbb{R}$, population size μ , adaptation rate $\alpha = 0.1$

$t \leftarrow 1$, initialize $\mathcal{P} = \{\mathbf{x}_1, \dots, \mathbf{x}_\mu\}$ randomly;

Initialize internal parameters $m_F \leftarrow 0.5$ and $m_C \leftarrow 0.5$;

while The termination criteria are not met **do**

for $i \in \{1, \dots, \mu\}$ **do**

$F_i \sim \text{CauchyDist}(m_F, 0.1)$ and $C_i \sim \text{NormalDist}(m_C, 0.1)$;

 Randomly select r_1, r_2, r_3 from $\{1, \dots, \mu\} \setminus \{i\}$ s.t. $r_1 \neq r_2 \neq r_3$;

 Mutant vector $\mathbf{v}_i \leftarrow \mathbf{x}_{r_1} + F_i (\mathbf{x}_{r_2} - \mathbf{x}_{r_3})$;

 Child $\mathbf{u}_i = (u_{i,1}, \dots, u_{i,n})^\top$, randomly select j_{rand} form $\{1, \dots, n\}$;

for $j \in \{1, \dots, n\}$ **do**

if $\text{rand}[0, 1] \leq C_i$ **or** $j = j_{\text{rand}}$ **then** $u_{i,j} \leftarrow v_{i,j}$;

else $u_{i,j} \leftarrow x_{i,j}$;

for $i \in \{1, \dots, \mu\}$ **do**

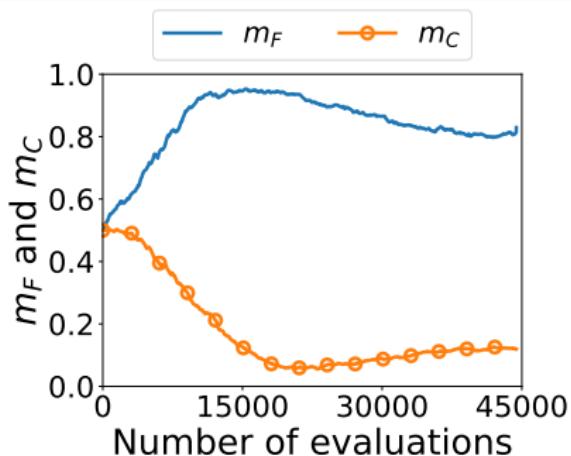
if $f(\mathbf{u}_i) \leq f(\mathbf{x}_i)$ **then** $\mathbf{x}_i \leftarrow \mathbf{u}_i$;

$m_F \leftarrow (1 - \alpha)m_F + \alpha \text{Lmean}(\mathcal{S}_F)$ and $m_C \leftarrow (1 - \alpha)m_C + \alpha \text{mean}(\mathcal{S}_C)$;

$t \leftarrow t + 1$;

Behavior of the internal parameters m_F and m_C in JADE

(c) Rastrigin ($n = 10$)



(d) Rosenbrock ($n = 10$)

